Application of Artificial Neural Network in Assessing Fill Slope Stability

An-Jui. Li, Kelvin Lim, Chien-Kuo Chiu, Benson Hsiung

Abstract—This paper details the utilization of artificial intelligence (AI) in the field of slope stability whereby quick and convenient solutions can be obtained using the developed tool. The AI tool used in this study is the artificial neural network (ANN), while the slope stability analysis methods are the finite element limit analysis methods. The developed tool allows for the prompt prediction of the safety factors of fill slopes and their corresponding probability of failure (depending on the degree of variation of the soil parameters), which can give the practicing engineer a reasonable basis in their decision making. In fact, the successful use of the Extreme Learning Machine (ELM) algorithm shows that slope stability analysis is no longer confined to the conventional methods of modeling, which at times may be tedious and repetitive during the preliminary design stage where the focus is more on cost saving options rather than detailed design. Therefore, similar ANN-based tools can be further developed to assist engineers in this aspect.

Keywords—Landslide, limit analysis, ANN, soil properties.

I. INTRODUCTION

SLOPE stability is a common geotechnical problem that has received attention in the past decades [1]-[4]. The stability problems of natural slopes, fill slopes (such as embankments, earth dams and levees), or cut slopes are commonly encountered in civil engineering projects. Fill slopes in particular often appear in the construction of embankments and highways where soils (fill materials) are placed on an existing layer of foundation [5], [6]. An example of such slopes can be seen in the illustration of Fig. 1.

The very first set of stability charts were produced by Taylor [7], and hence, begun the trend of the use of stability charts as design tool in slope stability problems. It should be noted there are some limitations to chart solutions, and these limitations include accuracy issues that may arise from interpolation and/or manual reading of the charts. In addition, the results of Lim et al. [8] revealed that the slope probability of failure ($P_f$) is extremely cumbersome to be predicted precisely, if there is more than one soil layer in a slope.

Shahin et al. [9] indicated that ANN has been successfully used to solve various geotechnical engineering problems such as pile capacity, modeling soil behavior, site characterization, earth retaining structures and others. The techniques are mainly used to estimate some factors that are difficult to be measured directly or accurately. Moreover, compared with the conventional trial-and-error method, they involve a considerably shorter computation time. As highlighted by Silva et al. [10], risk-based analyses are not as well adopted because of the difficulty in performing a probabilistic analysis by rigorous mathematical means. In this paper, we aim to develop an accurate and quick solution to analyze the stability of two-layered undrained clay slopes. At the same time, simple reliability assessments of the slopes will be also provided.

![Fig. 1 Example of an embankment slope](image)

II. PREVIOUS STUDIES

A. Slope Stability Investigations

Limit equilibrium method (LEM) is one of the most popular methods to evaluate the stability of slopes [11]. Currently, LEM has been applied to both two dimensional (2D) and three dimensional (3D) slope stability analyses. It is known, however, that in using LEM, the potential slip surface must be assumed before calculating the factor of safety ($F_s$) for the slope. Moreover, arbitrary assumptions need to be made regarding forces between two slices. Because of these assumptions, the results are often questioned. In particular, the slip surfaces must be assumed for some cases based on experience or judgment [12], [13].

Finite element method (FEM) is also a popular approach used for slope analyses. Duncan [1] indicated that FEM is a useful tool to calculate stresses, movements, as well as pore pressure and other characteristics of earth masses during construction without previously assuming the potential sliding surface. To estimate the slope stability and obtain its factor of safety by using finite-element analysis, the strength reduction method (SRM) is widely used. However, the failure load is determined subjectively, generally based on observation of the

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B. Applications of ANN to Slope Stability

Recently, optimization techniques, such as ANNs and genetic algorithms (GAs), have been applied to many geotechnical investigations, including the evaluation of soil and rock properties [19], [20], anchor and bearing capacity [21], [22], ground movements [23], [24], and slope failures [25], [26]. Among the available AI techniques, ANNs are the most commonly used technique in geotechnical engineering. The techniques are mainly used to estimate factors that are difficult to measure directly or accurately; moreover, compared with the conventional trial-and-error method, they involve a considerably shorter computation time [27]. In recent years, ANNs have been successfully applied to slope stability assessment. The studies of Abdalla et al. [28] and Gelisli et al. [29] demonstrated that ANNs can be used to predict the factors of safety of slopes reasonably. However, only single-layer homogeneous cohesive-frictional soil slopes were investigated in their studies. The solutions for fill slopes based on ANNs do not exist so far. Therefore, this study aims to take advantage of ANNs for fill slope assessments.

III. METHODOLOGY

A. Finite Element Limit Analysis Methods

By using both numerical upper and lower bound limit analysis methods [16]–[18] for slope stability evaluations, Shiau et al. [30] investigated the effects of external loading on undrained slopes. Moreover, Kim et al. [31] and Loukidis et al. [32] proposed sets of stability charts for nonhomogeneous soil slopes and cohesive-frictional soil slopes subjected to pore pressure and seismic loadings, respectively.

To simplify the problem, only 2D cases are considered in this study. The illustration of the slope stability problem investigated herein is shown in Fig. 2. The slope geometry analyzed for the filled slopes with two purely cohesive layered soils can be seen in Fig. 2. It should be noted that the undrained shear strength in Region 1 ($c_{u1}$) and Region 2 ($c_{u2}$) are with different values. In this study, for given slope height ($H$), slope angle ($\beta$), and undrained shear strength ($c_{u1}$ and $c_{u2}$), the optimized solutions of the UB and LB programs can be carried out with respect to the unit weight, $\gamma$. Recently, Qian et al. [33] proposed a non-dimensional stability number, $N_{2c}$, as shown in (1), where $F$ is the slope factor of safety. It should be noted that the magnitude of $F$ obtained by (1) is generally different from that by the conventional LEM due to their different definitions.

$$N_{2c} = \frac{c_{u1}}{\gamma H}$$ (1)

For the upper bound (UB) theorem, the power dissipated by any kinematically admissible velocity field can be equated to the power dissipated by the external loads to give a rigorous UB on the true limit load [15]. The lower bound (LB) theorem states that the admissible stress field must fulfill equilibrium, the stress boundary condition, and yield conditions [14]. For 2D limit analysis modeling, the mesh generation must follow two important guidelines: (1) the overall mesh dimensions are adequate to contain the computed stress field (LB) or velocity/plastic field (UB); and (2) there is an adequate concentration of elements within critical regions. The final finite-element mesh arrangements (both UB and LB) were selected only after considerable refinements were made. The typical finite-element mesh for the UB and LB limit analysis is displayed in Fig. 3.

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B. ANN

Since ANN has been proven to be a universal approximator, the linear combinations of the nonlinear neurons and weights, after proper training or selections, can approximate any linear or nonlinear functions. As a result, a single hidden layer feed forward neural network is chosen herein, whereby the inputs of the trained ANN are continuously mapped to the outputs in a differentiable manner.

Fig. 4 illustrates a single-hidden layer feed forward neural network, which will serve as a basic framework for our study. Then in order to expedite the training process, ELM [34] is
used, which is an improvement in terms of speed over the commonly used gradient-based back propagation (BP) algorithm. Basically, the BP algorithm compares the degree of error between ANN output and the desired output and slowly minimizes the error, and therefore, is time consuming.

![Fig. 4 Single-hidden layer neural network](image)

However, the use of the ELM training algorithm facilitates the random assignment of the weights of the ANN and the consideration of the ANN as a linear system. However, the main feature of the ELM algorithm is its batch learning capability; it trains the ANN in a single global optimization operation, and therefore, the learning speed of the ELM can be considerably faster than the BP. The input data vector \( x(k) \) and the output data vector \( y(k) \) can be expressed as follows:

\[
x(k) = \begin{bmatrix} x_1(k) \\ x_2(k) \\ \vdots \\ x_n(k) \end{bmatrix}
\]

and the \( i \)th output of the neural network, \( y_i(k) \) can be expressed as:

\[
y_i(k) = \sum_{j=1}^{M} \alpha_j \phi(w_{ji}^T x(k)) = \xi_i^T(k) \alpha_i
\]

Suppose we have \( N \) training input vectors \( x(1), x(2), \ldots, x(N) \) and \( N \) desired output data vectors \( y(1), y(2), \ldots, y(N) \) for training the ANN, as in Fig. 1. The following derivations can be easily obtained:

\[
\begin{bmatrix}
y^T(1) \\
\vdots \\
y^T(N)
\end{bmatrix} = \begin{bmatrix} \xi_1^T(1) \\
\vdots \\
\xi_N^T(N) \end{bmatrix} \alpha = G \alpha
\]

with

\[
G = \begin{bmatrix} \phi(w_{11}^T x(1)) & \ldots & \phi(w_{1n}^T x(1)) \\
\vdots & \ddots & \vdots \\
\phi(w_{m1}^T x(N)) & \ldots & \phi(w_{mn}^T x(N)) \end{bmatrix}
\]

The output weight matrix, \( G \), of the ANN can be computed in a single iteration, where

\[
\alpha = (G^T G)^{-1} G^T y_d
\]

and

\[
y_d = \begin{bmatrix} y_d^T(1) \\
\vdots \\
y_d^T(N) \end{bmatrix}
\]

IV. RESULTS AND DISCUSSIONS

Based on the developed tool, a couple of parametric studies have been done to show the benefits and also the efficiency of the tool. The slope parameters of the first parametric study are as follows: \( c_{u1}/c_{u2} \) ratio = 4, \( c_{u1} = 50 \) kN/m², a unit weight \( \gamma = 18 \) kN/m³, and a depth factor \( d/H = 2 \). Further to that, varying slope heights and slope angles are used to demonstrate the convenience of the tool. Additionally, the coefficients of variation (COVs) of the undrained shear strength of soil are also varied. The other parameters used can be seen in Table I.

<table>
<thead>
<tr>
<th>Case #</th>
<th>Slope angle (°)</th>
<th>Slope Height (m)</th>
<th>COV of ( c_{u1} )</th>
<th>COV of ( c_{u2} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>15</td>
<td>3</td>
<td>0.1</td>
<td>0.2</td>
</tr>
<tr>
<td>2</td>
<td>30</td>
<td>4</td>
<td>0.2</td>
<td>0.1</td>
</tr>
<tr>
<td>3</td>
<td>45</td>
<td>5</td>
<td>0.1</td>
<td>0.3</td>
</tr>
<tr>
<td>4</td>
<td>60</td>
<td>6</td>
<td>0.2</td>
<td>0.3</td>
</tr>
<tr>
<td>5</td>
<td>75</td>
<td>7</td>
<td>0.3</td>
<td>0.3</td>
</tr>
</tbody>
</table>

The first thing we can observe from Table II is that the stability numbers produced by our developed tool are very similar to the targeted stability numbers (targeted stability numbers are obtained from the numerical analysis). Based on the stability numbers and also the slope parameters, the factors of safety for the respective slope heights are obtained. The factors of safety can be obtained as \( F = NH/\gamma c_{u} \). As expected, the results show that the factor of safety decreases as the slope height increases. In fact, the advantage of the tool allows for the probability of failure to be obtained in tandem with the factor of safety. For instance, under column 5 of Table II, the probability of failure can be seen to increase as the factor of safety decreases. In this case, the probability of failure is also affected by the coefficient of variation. For example, while the factor of safety for the 3rd case is \( F = 1.17 \), the slope is with a probability of failure of approximately 0.14. In a slope design, factor of safety less than unity is undesirable. This is clearly reflected in case 4 and case 5 where the slopes are considered as unsafe.
there may be a two in 10 chance that the slope may fail. In fact, relevant in slope design. For example, the results show that a defining it in terms of probability of failure. Therefore, using approximately 1.2 is barely sufficient for a safe slope design. instance, many would think that a factor of safety of picture in addition to the conventional factor of safety. For conclusion can be made. This newly developed tool introduces risk may be further reduced if a more thorough soil design. Additionally, the influence of uncertainties in soil properties was also demonstrated. Particularly, in today’s industry where clients are focused on cost reduction whereby quick justification is required to convince the clients in investing in a proper and thorough soil investigation.

V. CONCLUSION

This study adopts the techniques, ANN to develop a fast evaluation tool for fill slope stability analyses. The training data are obtained based on the finite element upper and lower bound limit analysis solutions. The developed tool can provide prompt fill slope stability estimations and its probability of failure. It is very useful for practicing engineers, particularly for decision making.

REFERENCES


