

SOTM: A New Cooperation Based Trust Management System for VANET

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Abstract : Security and trust management in Vehicular Ad-hoc NETWORKS (VANET) is a crucial research domain which is the scope of many researches and domains. Although, the majority of the proposed trust management systems for VANET are based on specific road infrastructure, which may not be present in all the roads. Therefore, road security should be managed by vehicles themselves. In this paper, we propose a new Self Organized Trust Management system (SOTM). This system has the responsibility to cut with the spread of false warnings in the network through four principal components: cooperation, trust management, communication and security.

Keywords : active vehicle, cooperation, trust management, VANET

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