

Controller Design Using GA for SMC Systems

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Abstract : This paper considers SMCs using linear feedback with switched gains and proposes a method which can minimize the pole perturbation. The method is able to enhance the robustness property of the controller. A pre-assigned neighborhood of the 'nominal' positions is assigned and the system poles are not allowed to stray out of these bounds even when parameters variations/uncertainties act upon the system. A quasi SMM is maintained within the assigned boundaries of the sliding surface.

Keywords : parameter variations, pole perturbation, sliding mode control, switching surface, robust switching vector

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