H∞ Takagi-Sugeno Fuzzy State-Derivative Feedback Control Design for Nonlinear Dynamic Systems

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Abstract : This paper considers an $\langle em \rangle H \langle em \rangle \langle sub \rangle \& infin; \langle sub \rangle TS fuzzy state-derivative feedback controller for a class of nonlinear dynamical systems. A Takagi-Sugeno (TS) fuzzy model is used to approximate a class of nonlinear dynamical systems. Then, based on a linear matrix inequality (LMI) approach, we design an <math>\langle em \rangle H \langle em \rangle \langle sub \rangle \& infin; \langle sub \rangle TS fuzzy state-derivative feedback control law which guarantees <math>\langle em \rangle L \langle em \rangle \langle sub \rangle 2 \langle sub \rangle$ -gain of the mapping from the exogenous input noise to the regulated output to be less or equal to a prescribed value. We derive a sufficient condition such that the system with the fuzzy controller is asymptotically stable and $\langle em \rangle H \langle em \rangle \langle sub \rangle \& infin; \langle sub \rangle$ performance is satisfied. Finally, we provide and simulate a numerical example is provided to illustrate the stability and the effectiveness of the proposed controller.

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