# Biometric Steganography Using Variable Length Embedding

Souvik Bhattacharyya, Indradip Banerjee, Anumoy Chakraborty, Gautam Sanyal

Abstract-Recent growth in digital multimedia technologies has presented a lot of facilities in information transmission, reproduction and manipulation. Therefore, the concept of information security is one of the superior articles in the present day situation. The biometric information security is one of the information security mechanisms. It has the advantages as well as disadvantages. The biometric system is at risk to a range of attacks. These attacks are anticipated to bypass the security system or to suspend the normal functioning. Various hazards have been discovered while using biometric system. Proper use of steganography greatly reduces the risks in biometric systems from the hackers. Steganography is one of the fashionable information hiding technique. The goal of steganography is to hide information inside a cover medium like text, image, audio, video etc. through which it is not possible to detect the existence of the secret information. Here in this paper a new security concept has been established by making the system more secure with the help of steganography along with biometric security. Here the biometric information has been embedded to a skin tone portion of an image with the help of proposed steganographic technique.

*Keywords*—Biometrics, Skin tone detection, Series, Polynomial, Cover Image, Stego Image.

#### I. INTRODUCTION

N this extremely digitalized globe, the Internet provides an Limportant responsibility for data transmission and sharing. So therefore the safety and security of communication system is obligatory. The "Information Hiding" is one of the catching focuses for the safety and security. Subsequently the theory of Cryptography [1] and watermarking [2] has been developed. The word "Security" is a very communicable word from prehistoric age and the meaning has been changed in modern age, because the research in reverse engineering techniques has been increased the processing power which rise the fight between researches in cryptanalysis [3] and watermarking detection [4]. To crack these troubles the conception of Steganography [5] has been formed by the researchers. Steganography is one kind of information hiding appliance that can conceal secret information within a normal carrier media, such as text, image, audio, video, protocol etc. Steganography derived from the Greek words, literally means "covered writing". Steganalysis is a challenge to detect the existence and extract the hidden secret message from stego. If the existence of the hidden message is exposed, the goal of

Souvik Bhattacharyya and Anumoy Chakraborty are with the University Institute of Technology, The University of Burdwan, Burdwan (e-mail: souvik.bha@gmail.com, anu\_chak62@yahoo.co.in). steganography is crushed. Fig. 1 describes the types of steganography. Steganography have various techniques. Text Steganography [6] has the categories like Format-based, random & statistical generation, Linguistic methods and Quantum Approach [7]. In audio Steganography [8], messages are embedded into digitized audio signal which result slight alteration of binary sequence of the corresponding audio file. Several new approaches are studied in video data steganography literature [8]. In image steganographic techniques various ways are used, which are as follows [9]:

- Substitution technique in Spatial Domain: In this case the least significant bits of the cover item are replaced without modifying the complete cover image.
- Transform domain technique: Discrete Cosine Transform (DCT), Discrete Wavelet Transform (DWT) and Fast Fourier Transform (FFT) are used to hide information in transform coefficients of the cover images.
- Spread spectrum technique: The message is spread over a wide frequency bandwidth than the minimum required bandwidth to send the information.
- Statistical technique: Here the information is encoded by changing various numerical properties of cover image and the message bits are hidden in the block of cover image.
- Distortion technique: Information is stored by signal distortion.
- Pixel Mapping Method (PMM) [10], [11]: Embedding positions are selected by some function and Data embedding are done by mapping each two or four bits of the secret message in each of the neighbor pixel based on some features of that pixel.
- Pixel Factor Mapping (PFM) [12], [13]: Embed the four bits of secret message in a single pixel intensity based on the maximum prime factor value of pixel intensity. It works in spatial and frequency domain with high embedding capacity.

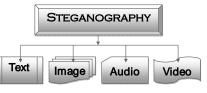


Fig. 1 Types of Steganography

Automatic recognition system of an individual has been derived from the physiological and behavioral [14]–[19] characteristic which describes the Biometric security system. The term "biometrics" is derived from a Greek words bio means "life" and metric means "to measure". Biometric

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systems ascertain a person's identity based on pattern analyses carried out on specific human traits [15], [16]. Physiological based biometric systems consist of fingerprints, retina, iris, hand geometry, hand vein, ear shape and facial recognition systems [17]. These features are typically unchangeable exclusive of causing disturbance to human being. On the other hand, behavioural biometric characteristics are later stabilizing over a period of time. Some of the examples of behaviouralbased biometric systems are voice recognition, keystroke dynamics, signature verification and gait analysis. In case of a bank card, the biometric data can be used because there are a finite number of substitutes for a person i.e. as a person has only 10 fingers, two eyes, etc. Certifying the privacy and security of biometric data, users will be doubtful to accept the technology if information could hypothetically be tampered with, stolen or misused. [18]. Generations wise biometric techniques have been well-appointed in [19]. Fig. 2 describes the classification of biometric techniques. In existing system there are various methods have been developed by most of the researchers using different biometric features.

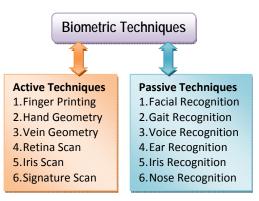


Fig 2 Classification of biometric techniques

This is a new steganography technique apart from the other steganographic techniques. In this work the biometric thumb image is embedded to a skin tone portion of an image as bit stream of two to four bits combinations. The pixel selection technique is to find out the skin tone portion from the cover image. This method can also extract biometric information even after noise addition in stego image. The developed contribution is a novel biometric steganography technique. Rest of the paper has been organized as following sections: Section II describes some related works on image steganography. Section III deals with proposed method and Section IV are for algorithms. In Section V experimental results are discussed and analyzed mathematically. Section VI makes a comparison and Section VII draws the conclusion.

#### II. ASSOCIATED WORK

#### A. Image Steganography Techniques

The image steganography can be possible in two domains, one is Spatial and another is frequency domain. There are various techniques and modules developed by different researchers. Some of them are discussed below:

#### 1) Spatial Domain Technique

The common techniques in this domain is least-significantbit (LSB) [20] where directly replace the LSBs of the coverimage with message bits. The pixel-value differencing (PVD) method proposed by Wu and Tsai [21] can successfully provide both high embedding capacity and outstanding imperceptibility for the stego-image. Among them Chang et al. [22] proposes a new method using tri-way pixel-value differencing which is better than original PVD method with respect to the embedding capacity and PSNR. In 2004, Potdar et al. [23] proposes GLM (Gray level modification) technique which is used to map data by modifying the gray level of the image pixels. Hong and Chen [24] introduced a new method based on pixel pair matching (PPM).

#### 2) Frequency Domain Technique

In data hiding based on JPEG [25] method, the cover image is broken down into a set of blocks and performed the discrete cosine transform (DCT) on each block. The transformed coefficients are quantized with the help of default quantization table of JPEG. The secret data is embedded into the quantized coefficients. Kobayashi et al. [26] embed one secret bit into one 8×8 DCT block. Jpeg-Jsteg [27], the secret data is embedded into the LSB of the quantized DCT coefficients whose values are not 0, 1, or -1. Mutto and Kumar proposed a Jpeg-Jsteg algorithm based on T-codes, which are belongs to the families of variable-length codes (VLC) that exhibit extraordinarily strong tendency towards self synchronization. The concepts of simple Tcodes were given by M.R. Titchner [28]. K. B. Raja et al. [29] embedded in the wavelet coefficients of the cover image. Radovan Ridzon et al. [30] presented a technique to hide secret information inside the cover image. Chang et al. [31] embed the secret data into the middle frequency part of the quantized DCT coefficients.

#### B. Biometric Information Security:

Biometrics system intends to recognize an individual through physiological or behavioral attributes, for instance face, fingerprint, iris, retina and DNA also [32]. In biometric technique there are various ways and all biometric techniques differ according to security level, user acceptance, cost and performance. Some of the techniques are describe below:

#### 1) Fingerprints

Fingerprint [33] is one of the biometric securities, which is based on fingertip pattern recognition. There are three basic patterns of fingerprint ridges: 1) Arch: Ridges enter from one side of the finger, forming in the center and exit the other side of the finger. 2) Loop: Ridges enter from one side of a finger then form a curve and then exit on that same side. 3) Whorl: The ridges form circularly around a central point on the finger. There are several approaches to fingerprint verification. Some of them follow the conventional method of matching finer points; others use straight pattern matching mechanism. Some of fingerprint verification approaches can detect a live finger where as some cannot. Various fingerprint devices are available than any other biometric system. Scientists have found that family members are inherited patterns, so they often share the same general fingerprint patterns.

#### 2) Retina

Analyzing the complex structure of the capillaries that is the layer of blood vessels at retina which is not entirely genetically determined i.e. back of eye is involved in this procedure. For that reason each person's retina is unique. Find out the unique patterns of the retina using low intensity light source through an optical coupler is the process to identify. The technology can work well but it is not convenient if human uses glasses or having close contact with the reading device [34]. The Advantages in this technique is Low rates of false positives and false negative. This technique is highly reliable because no two people have the same retinal pattern. But the measurement accuracy affected by various eye diseases like cataracts, diabetes and glaucoma or retinal degenerative disorders.

#### 3) Face

Face biometry [35] depending on analyzing facial characteristics. It involves a digital camera to grow a facial image of the user for authentication. In this system it automatically identifying or verifying a person from an image. One of the ways to do this is to compare some selected facial features from the image and a facial database. Among the different biometric techniques, facial recognition may not be the most reliable and efficient.

#### 4) Hand Geometry

In this mechanism the shape of the human hand is computed and analyzes [36]. Hand geometry is based on the palm and fingers structure, width of the fingers in different places, length of the fingers, thickness of the palm area, etc. while these measurements are not very distinctive among people, so hand geometry be capable for identity verification, i.e. personal authentication. This biometric system recommends a good stability of performance characteristics and is reasonably straightforward to apply. This is suitable where lots of users are there in the system and they access infrequently. In this system the accuracy level is very high and performance is flexible.

#### 5) Nose

The nose biometric technique [37] works through features extracting from a nose and by the help of various classification techniques. Geometric ratios and nose ridge shape both demonstrate the procedures of nose's biometric. The nose's biometric is largely unknown and for that reason it is very flexible in performance but the recognition procedure is currently far lower than other biometrics.

#### 6) Ear

One of interesting authentication technique is ear biometric security. Analyzing ear shape and area measurement of a human can identify people [38]. Ear biometrics appears as a well-organized biometric method for human identification and could be used like other biometrics because the human ear goes through little changes as course of age. Now a day the 2D

and 3D domain are presented in this biometric feature.

#### 7) Signature

Signature recognition is one of the behavioural biometric systems. Signature signing features like writing speed, velocity and pressure are used for identifications. Signature verification devices are logically accurate in operation and lend themselves to applications where a signature is an accepted identifier [39]. It can be operated in two different ways:

- Static: Users write their signature on paper then digitize through a scanner or camera and the biometric system recognizes the signature analyzing its shape.
- Dynamic: Users write their signature in a digitizing tablet.

#### 8) Iris

In this iris-based biometric [40], the system can analyzing features using mathematical pattern-recognition techniques. It stores the measurement of the colored ring of tissue surrounds the pupil of eye. Iris biometrics uses a fairly conventional camera element and obliges no close contact among the user and reader. In this system, first localize the inner and outer boundaries of the iris (pupil and limbus) from an eye image. Then detect and exclude eyelids, eyelashes and specular reflections that often unused parts of the iris. The set of pixels contain the iris, normalized by a rubber-sheet model to compensate for pupil dilation or constriction, then analyzed to extract bit pattern information which is needed for compare of two iris images. This system work with glasses and few devices can work well in identification mode also.

#### 9) Voice

Voice biometrics [41] has the most probable for enlargement, because it requires no new hardware—most PCs already contain a microphone. Speaker recognition is the identification of the human beings that who is speaking. By the help of characteristics of their voices the verification process occurs. But the noisy voice can affect verification.

#### 10) Vein geometry

In this technique the vein of hand, vein of finger, vein of palm etc are used for authentication purpose. It is not observable under visible light so the security is very high. The infrared sensors used for captured and detect the structure of the vein patterns. There are two kinds of imaging technology have been used to develop this system, which are Far-infrared (FIR) and Near-infrared (NIR). Visibility of the vein structure depends on different issues like age, thickness of the skin, ambient temperature, physical activity, depth of the veins under the skin. Additionally, skin texture for instance moles, warts, scars and hair can also distress the imaging excellence of the veins. L. Wang et al. [42] proposed a verification system of human beings using the thermal-imaged vein pattern in the back of hand. A. Kumar et al. [43] presents a technique which can authenticate a person based on minutiae matching of vein junction points.

#### III. PROPOSED METHOD

In this contribution a spatial domain steganographic technique has been developed for embedding biometric information in bit stream format. This procedure is describing in details with the habit of several fragments.

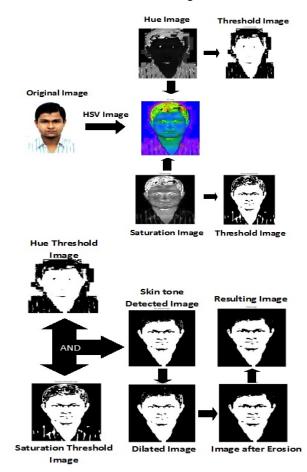


Fig. 3 Technique of Pixel Selection

#### A. Pixel Selection

To select the embedding pixel of the cover image, the biometric algorithm has been used. Through this steganographic system the PSNR value is comparatively better because some special portion of image is used for embedding instead of embedding data anywhere in the image. In this system the skin region of the image has been used for embedding of secret data. There are mainly two kinds of color spaces are suitable for biometric operations which are HSV (Hue, Saturation and Value) and YCbCr (Yellow, Chromatic Blue, Chromatic Red) spaces. The system detects the skin color with the help of skin detector and skin classifier. Skin detector can convert the RGB color space into appropriate color space HSV, as because it is more related to human colour perception. For skin detection a threshold should be chosen as the purpose of hue range= $[h_1, h_2]$  and sat\_range= $[S_1, S_2]$ . Then skin classifier classifies the pixels in the cover image to skin and non skin pixels by defining a boundary. The skin detection algorithm produces a mask which is simply a black and white pixel with the help of threshold, which has a predefined range associated with the target skin pixel values. Most of the researchers are using the threshold as hue\_range=[0,0.11] and sat\_range=[0.2,0.7]. Fig. 3 illustrates the pixel selection process. After getting the Hue thresholded image and Saturation thresholded image the system perform simple AND operation to detect the skin tone by white marked pixels other pixels are black as it is seen in the Fig. 3. After getting the skin tone detected image the system can remove noise by a morphological filter performing two operations such as Dilation and Erosion. Dilation means expand the skin regions to detect imperfections. Then erosion operation will remove the imperfection to get a better resulting image. Thus the system results the noise free skin tone detected image and continue its operation for further processing.

#### B. Embedding Space Selection:

In this performance the system follows embedding space varies from pixel to pixel. To get the embedding space of a pixel of the cover image the system uses a series of integers and thus the system adds the squared value of integers up to the below next value  $a_{ij}$  of the pixel *Pix*<sub>ij</sub> and also do the same up to the next above value  $\beta_{ij}$  of the pixel *Pix*<sub>ij</sub>. As for example,  $P_{ix_{ij}} = 127$ 

Then, 
$$\alpha_{ij} = 1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 6^2 = 91\langle 127 \rangle$$
 and  
 $\beta_{ij} = 1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 6^2 + 7^2 = 140 \rangle 127$ .

Then the system calculate the mid value by

$$\gamma_{ij} = \left(\alpha_{ij} + \beta_{ij}\right)/2 \tag{1}$$

and if  $Pix_{ij}$  is less than or equal to the mid value  $\gamma_{ij}$  then it get the subtracted value

$$\delta_{ij} = \left( P \, i x_{ij} - \alpha_{ij} \right) \tag{2}$$

else

$$\delta_{ij} = \left(\beta_{ij} - P i x_{ij}\right) \tag{3}$$

as embedding space. Thus after getting the embedding space for each pixel  $Pix_{ij}$  the system will further approach for embedding. Fig. 4 determines the embedding space.

#### C. Embedding:

To make the steganalysis difficult, this method does not embed the message bit directly to the image and it is done with the help of polynomial functions. Then the value getting from the polynomial is embedded into those pixels of the cover image according to its availability of embedding space.

For a bit stream Bit\_s=1010111 the embedding procedure is shown in Fig. 5.

The embedding polynomial used here is as follows:

$$\sum^{n} = x^{n} (k + bit_{1}) + x^{n-1} (k + bit_{2}) + x^{n-2} (k + bit_{3}) + \dots + x (k + bit_{n}) (4)$$

where,  $bit_n = n^{th} bit$  of remainder bit stream. Thus the system embed the bit stream according to every pixels embedding

space  $\delta_{ij}$  and if there is not enough embedding space  $\delta_{ij}$  then the system go for next pixel of the plane and if data is fully embedded in that plane then the system perform embedding in next plane.

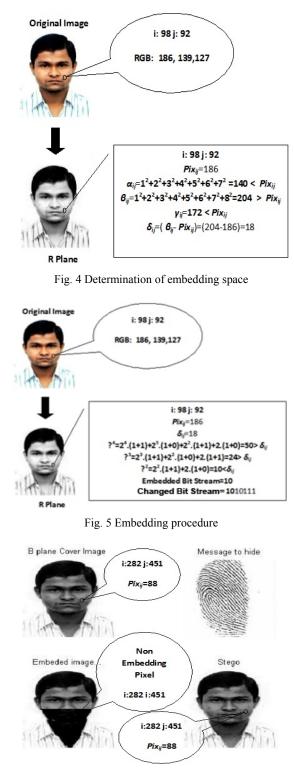


Fig. 6 Non Embedding positions

D.Non Embedding Portion:

The system does not incorporate any stop bit to denote the

end of bit stream embedding. One pixel can have a value which falls in much difference from other pixels. But the system sets the value of non embedding pixels in such a manner so that its difference from original cover pixel is one or zero as well as there no data can be extracted at the extraction time. Fig. 6 shows the non embedding positions. Fig. 7 illustrates that how to make the Stego from the cover image and Extract the secret Image.

#### E. Variable Length Message Embedding:

The system embed a variable length message bits depending upon the availability of embedding space and bit stream also so that those bits of message bit stream is embedded for which  $\sum^{n}$  is less than  $\delta_{ij}$ .

$$\gamma_{ij} = \left(\alpha_{ij} + \beta_{ij}\right) / 2 \tag{5}$$

if  $P_{ix_{ij}} \leq \gamma_{ij}$ , where *Pix*<sub>ij</sub> is the pixel intensity and  $\delta_{ij}$  is the embedding space.

$$\delta_{ij} = \left( P \, i x_{ij} - \alpha_{ij} \right) \tag{6}$$

else

$$\delta_{ij} = \left(\beta_{ij} - P i x_{ij}\right) \tag{7}$$

$$\sum_{n=1}^{n} x^{n} (k + bit_{1}) + x^{n-1} (k + bit_{2}) + x^{n-2} (k + bit_{3}) + \dots + x (k + bit_{n})$$
(8)

where, bit<sub>n</sub>=n<sup>th</sup> bit of remainder bit stream.

Some of the following cases have been presented below with respect to variable message bit stream 's'-

#### Case 1:

For a bit stream s=1101010111...Pix<sub>ij</sub> = 173

Embedding Space 
$$\delta_{ij} = 31$$
.  

$$\sum^{4} = 2^{4} (1+1) + 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 56 \rangle \delta_{ij}$$

$$\sum^{3} = 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 24 \langle \delta_{ij}$$
Embedded Bit Stream=110

$$Pix_{ij} = 186$$

Embedding Space 
$$\delta_{ii} = 18$$

$$\sum^{4} = 2^{4} (1+1) + 2^{3} (1+0) + 2^{2} (1+1) + 2 (1+0) = 50 \rangle \delta_{ij}$$
  

$$\sum^{3} = 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 24 \rangle \delta_{ij}$$
  

$$\sum^{2} = 2^{2} (1+1) + 2 (1+0) = 10 \langle \delta_{ij}$$

Embedded Bit Stream=10 Changed Bit Stream=<u>110</u>1010111

 $Pix_{ij} = 138$ 

Embedding Space  $\delta_{ii} = 2$ 

$$\sum^{4} = 2^{4} (1+1) + 2^{3} (1+0) + 2^{2} (1+1) + 2 (1+1) = 52 \rangle \delta_{ij}$$
  

$$\sum^{3} = 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 24 \rangle \delta_{ij}$$
  

$$\sum^{2} = 2^{2} (1+1) + 2 (1+0) = 10 > \delta_{ij}$$
  

$$\sum^{1} = 2 (1+1) = 4 \rangle \delta_{ij}$$

#### Embedded Bit Stream=Null Changed Bit Stream=1101010111

Case 2:

For a bit stream s=1001001101.... *Pix*  $_{ii} = 173$ Embedding Space  $\delta_{ii} = 31$  $\sum_{i=1}^{4} = 2^{4} (1+1) + 2^{3} (1+0) + 2^{2} (1+0) + 2 (1+1) = 48 \delta_{ii}$  $\sum^{3} = 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+0) = 22 \langle \delta_{ij} \rangle$ Embedded Bit Stream=100

## Changed Bit Stream=1001011101

 $Pix_{ij} = 186$ 

Embedding Space  $\delta_{ii} = 18$ 

 $\sum^{4} = 2^{4} (1+1) + 2^{3} (1+0) + 2^{2} (1+1) + 2 (1+1) = 52 \rangle \delta_{ij}$  $\sum^{3} = 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 24 \rangle \delta_{ij}$  $\sum^{2} = 2^{2} (1+1) + 2 (1+0) = 10 \langle \delta_{ii}$ Embedded Bit Stream=10 Changed Bit Stream=1001000111  $Pix_{ii} = 138$ 

Embedding Space  $\delta_{ij} = 2$ 

$$\sum^{4} = 2^{4} (1+0) + 2^{3} (1+0) + 2^{2} (1+1) + 2 (1+1) = 36 \rangle \delta_{ij}$$
  

$$\sum^{3} = 2^{3} (1+0) + 2^{2} (1+0) + 2 (1+1) = 16 \rangle \delta_{ij}$$
  

$$\sum^{2} = 2^{2} (1+0) + 2 (1+0) = 6 \rangle \delta_{ij}$$
  

$$\sum^{1} = 2 (1+0) = 2 = \delta_{ij}$$

#### Embedded Bit Stream=0 Changed Bit Stream=1001000111

Thus from Case 1 and Case 2 it is seen that the system embed a bit stream of length 5 for Case 1 and of length 6 for Case 2. Hence it can conclude that the system embed a variable length message bit stream when bit stream is varied and embedding space  $\delta_{ii}$  remains same.

Now the author present variable length message embedding with respect to Embedding Space  $\delta_{ii}$ .

### Case 3: For a bit stream s=1101010111.... *Pix* $_{ii} = 173$ Embedding Space $\delta_{ii} = 31$ . $\sum^{4} = 2^{4} (1+1) + 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 56 \rangle \delta_{ij}$

 $\sum_{i=2}^{3} = 2^{3} (1+1) + 2^{2} (1+1) + 2 (1+0) = 26 \langle \delta_{ii} \rangle$ Embedded Bit Stream=110

#### Changed Bit Stream=1101010111

$$\begin{aligned} &\sum_{ij} = 18\\ &\sum_{ij} = 2^{4} (1+1) + 2^{3} (1+0) + 2^{2} (1+1) + 2 (1+0) = 50 \rangle \delta_{ij}\\ &\sum_{ij} = 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 24 \rangle \delta_{ij}\\ &\sum_{ij} = 2^{2} (1+1) + 2 (1+0) = 10 \langle \delta_{ij} \rangle \end{aligned}$$

Embedded Bit Stream=10 Changed Bit Stream=1101010111

$$Pix_{ij} = 138$$
  

$$\delta_{ij} = 2$$
  

$$\sum^{4} = 2^{4} (1+1) + 2^{3} (1+0) + 2^{2} (1+1) + 2 (1+1) = 52 \rangle \delta_{ij}$$
  

$$\sum^{3} = 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 24 \rangle \delta_{ij}$$
  

$$\sum^{2} = 2^{2} (1+1) + 2 (1+0) = 10 \rangle \delta_{ij}$$
  

$$\sum^{1} = 2 (1+1) = 4 \rangle \delta_{ij}$$
  
Embedded Bit Stream=Null  
Changed Bit Stream=1101010111

Case 4:

For a bit stream s=1101010010... *Pix*  $_{ii} = 187$ Embedding Space  $\delta_{ij} = 17$  $\sum^{4} = 2^{4} (1+1) + 2^{3} (1+1) + 2^{2} (1+0) + 2 (1+1) = 56 \rangle \delta_{ii}$  $\sum_{i=1}^{3} = 2^{3} (1+1) + 2^{2} (1+1) + 2 (1+0) = 26 \rangle \delta_{ii}$  $\sum_{i=1}^{2} = 2^{2} (1+1) + 2 (1+1) = 12 \langle \delta_{ii} \rangle$ Embedded Bit Stream=11

#### Changed Bit Stream=1101010111

$$Pix_{ij} = 185$$
  

$$\delta_{ij} = 19$$
  

$$\sum^{4} = 2^{4} (1 + 0) + 2^{3} (1 + 1) + 2^{2} (1 + 0) + 2 (1 + 1) = 40 \rangle \delta_{ij}$$
  

$$\sum^{3} = 2^{3} (1 + 0) + 2^{2} (1 + 1) + 2 (1 + 0) = 18 \langle \delta_{ij}$$
  
Embedded Bit Stream=010  
Changed Bit Stream=110101111

$$Pix_{ij} = 160$$

$$\delta_{ij} = 20$$

$$\sum^{4} = 2^{4}(1+1) + 2^{3}(1+0) + 2^{2}(1+1) + 2 \quad (1+1) = 52 \ \rangle \delta_{ij}$$

$$\sum^{3} = 2^{3}(1+1) + 2^{2}(1+0) + 2 \quad (1+1) = 24 \ \rangle \delta_{ij}$$

$$\sum^{2} = 2^{2}(1+1) + 2 \quad (1+0) = 10 \ \langle \delta_{ij}$$
Embedded Bit Stream=10  
Changed Bit Stream=10  
Changed Bit Stream=11010101111

Thus from Case 3 and Case 4 it is seen that the system embed a bit stream of length 5 for Case 3 and of length 7 for Case 2. Hence it can conclude that the system embed a variable length message bit stream when bit stream is fixed and embedding space  $\delta_{ii}$  varied.

#### IV. Algorithms

#### A. Pixel Selection Algorithm by Skin Tone Detection:

- 1) Read the cover image
- 2) Convert the cover image into HSV colour space
- 3) Get the Hue Image Plane and Saturation Image Plane
- 4) Threshold the hue image plane and saturation image plane by setting the threshold hue\_range = [0,0.11] and sat\_range = [0.2,0.7] respectively.
- 5) Make AND operation between hue thresholded image and saturation thresholded image to get the skin tone detected image.
- 6) Make Dilation on the resulting image and then Erosion for noise removing.
- 7) Get the resulting skin tone detected image with white pixel at skin tone detected area otherwise black pixel at non skin tone detected area.

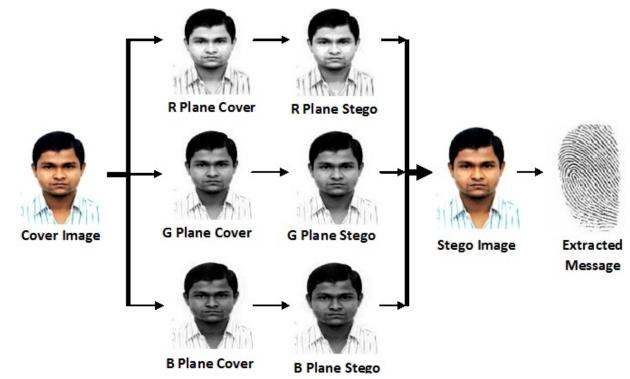


Fig. 7 Resulting Stego and Extracted Image

#### B. Algorithm for Embedding:

At first convert the message image into a bit stream for embedding.

For an M X N image

for i=1:M

for j=1:N

- For each pixel *Pix<sub>ii</sub>* in Original image:-
- 1)  $\alpha_{ij}$ :=Add the squared value of integers up to the sum value which is below next of  $Pix_{ij}$  value
- 2)  $\beta_{ij}$ :=Add the squared value of integers up to the sum value which is next above of  $Pix_{ij}$  value

3) 
$$\gamma_{ij} = (\alpha_{ij} + \beta_{ij})/2;$$

4) if  $Pix_{ij} \le \gamma_{ij}$  then  $\delta_{ij} := (Pix_{ij} - \alpha_{ij})$  else  $\delta_{ij} := (\beta_{ij} - Pix_{ij})$ 

5) Calculate the value for bit stream of length n = 4,3,2 and 1

$$\sum^{n} = x^{n} (k + bit_{1}) + x^{n-1} (k + bit_{2}) + x^{n-2} (k + bit_{3}) + \dots + x (k + bit_{n})$$
(9)

6) if  $\sum_{i=1}^{4} \leq \delta_{ij}$  then  $\mu_{ij} := \sum_{i=1}^{4} \delta_{ij}$ 

elseif 
$$\sum_{i=1}^{3} \leq \delta_{ij}$$
 then  $\mu_{ij} := \sum_{i=1}^{3}$   
elseif  $\sum_{i=1}^{2} \leq \delta_{ij}$  then  $\mu_{ij} := \sum_{i=1}^{2}$   
elseif  $\sum_{i=1}^{1} \leq \delta_{ij}$  then  $\mu_{ij} := \sum_{i=1}^{1}$   
7) if  $Pix_{ij} \leq \gamma_{ij}$  then  $S_{ij} := \alpha_{ij} + \mu_{ij}$  else  
 $S_{ij} := \beta_{ij} - \mu_{ij}$ ;  
end j  
end i  
Stego image S generates.

C.Algorithm for Extraction:

For an M X N Stego Image for i=1:M for j=1:N

For each pixel Pix<sub>ij</sub> in Original image:-

- 1)  $\alpha_{ij}$ :=Add the squared value of integers up to the sum value which is below next of  $Pix_{ij}$  value
- 2)  $\beta_{ij}$ :=Add the squared value of integers up to the sum value which is next above  $Pix_{ij}$  value

3) 
$$\gamma_{ij} := (\alpha_{ij} + \beta_{ij})/2$$

- 4) if  $S_{ij} \le \gamma_{ij}$  then  $\delta_{ij} := (S_{ij} \alpha_{ij})$  else  $\delta_{ij} := (\beta_{ij} S_{ij})$
- Get the equivalent bit stream of δ<sub>ij</sub> and go for next pixel.
   σ<sub>ij</sub>=bit stream
  - Extracted image is  $\sigma$ .

D. Algorithm for Non Embedding Portion:

For an M X N Image

for i=1:M

for j=1:N

1) If the pixel value  $Pix_{ij}$  is an odd number

if  $Pix_{ij} \leq \gamma_{ij}$ 

if  $\alpha_{ij} = even$ 

Pix<sub>ij</sub> unchanged

else if  $\alpha_{ij} = odd$ 

 $Pix_{ij}$  to next even number

elseif  $Pix_{ij} > \gamma_{ij}$ 

if  $\beta_{ij}$  =even

 $Pix_{ij}$  unchanged elseif  $\beta_{ij}$  =odd

 $Pix_{ii}$  to below next even number

2) If the pixel value  $Pix_{ij}$  is an even number :-

if  $Pix_{ij} \le \gamma_{ij}$ if  $\alpha_{ij}$  = even

 $Pix_{ij}$  to next odd number else if  $\alpha_{ij}$  = odd  $Pix_{ij}$  unchanged

elseif  $Pix_{ij} > \gamma_{ij}$ 

if  $\beta_{ij}$  =even  $Pix_{ij}$  to below next odd number elseif  $\beta_{ij}$  =odd  $Pix_{ij}$  unchanged

#### V. MATHEMATICAL ANALYSIS

In this segment the experimental results of the method has been described based on some techniques to evaluate the hiding performance. Since the capacity of hiding data depends upon the bit stream want to embed and embedding space depends upon the pixel value so that capacity varies from message to message thus different message image and imperceptibility of the stego image, these two techniques is used here for performance metric. Imperceptibility of the image is called the quality of image. The quality of stego image produced by the proposed method has been tested thoroughly based on various image similarity metrics namely MSE, PSNR, CORELATION, RMSE, SSIM, KL DIVG and ENTROPY. Figs. 10 to 16 show the graphical representation of calculated value of various similarity metrics for images. Various Techniques used to manage the difference between pixels. The techniques are described below:

#### A. Mean Square Error (MSE):

It is computed by averaging the squared intensity of the cover and stego image pixels. Equation (10) shows the MSE [44].

$$MSE = \frac{1}{NM} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} e(m,n)^2$$
(10)

where NM is the image size (N x M) and e(m,n) is the reconstructed image.

#### B. Peak Signal-to-Noise Ratio (PSNR):

A mathematical measure of image quality is Signal-tonoise ratio (SNR), which is based on the pixel difference between two images. The SNR measure is an estimate of quality of Stego image compared to cover image. PSNR [44] is shown in (11):

$$PSNR = 10\log_{10}\frac{S^2}{MSE}$$
 (11)

where, S stands for maximum possible pixel value of the image. If the PSNR is greater than 36 DB then the visibility looks same in between cover and stego image, so HVS not identified the changes.

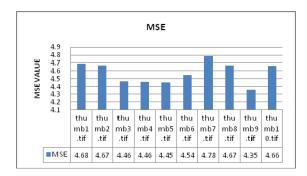


Fig. 8 MSE for various Secret Images

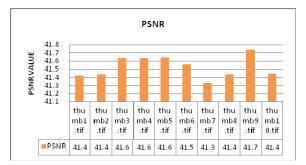


Fig. 9 PSNR for various Secret Images

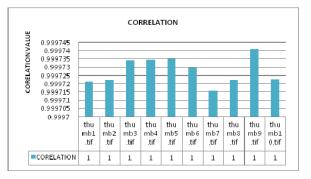


Fig. 10 Correlation for various Secret Images

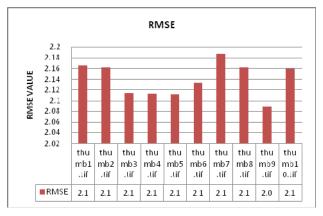


Fig. 11 RMSE for various Secret Images

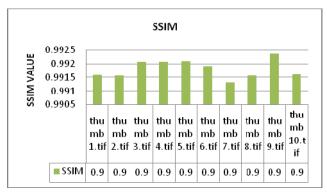


Fig. 12 SSIM for various Secret Images

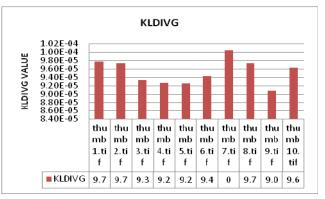


Fig. 13 K L Divergence for various Secret Images

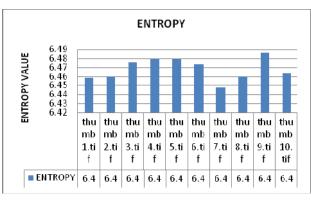


Fig. 14 Entropy for various Secret Images

#### C. Correlations:

Pearson's correlation coefficient [45] is widely used in statistical analysis as well as image processing. Here apply it in Cover and Stego images to see the difference between these two images. The Correlation shows in (12).

$$r = \frac{\sum_{i=1}^{n} (x_i - \overline{x}) \cdot (y_i - \overline{y})}{\sqrt{\sum_{i=1}^{n} (x_i - \overline{x})^2 \cdot \sum_{i=1}^{n} (y_i - \overline{y})^2}}$$
(12)

The Xi and Yi are the cover image and bar of X and Y are stego image positions. The correlation values are tens to 1 that means both the images are likely to same.

#### D.Root Mean Square Error (RMSE):

RMSE [46] is one kind of measurement of difference between values of Cover Image and the values of Stego Image. These differences are called residuals and the RMSE provide to combine them into a single measure of analytical power. The RMSE shows in (13):

$$RMSE = \sqrt{\frac{\sum_{i=1}^{n} (X_{obs,i} - X_{model,i})^{2}}{n}}$$
(13)

X<sub>obs,i</sub> and X<sub>model,i</sub> are two image vectors i.e. cover and stego.

#### E. Structural Similarity Index (SSIM):

Wang et al. [47], proposed Structural Similarity Index concept between original and distorted image. The Stego and Cover images are divided into blocks of 8 x 8 and converted into vectors. Then two means and two standard derivations and one covariance value are computed.

After that the luminance, contrast and structure comparisons based on statistical values are computed. Then The SSIM [26] computed between Cover and Stego images. SSIM shows in (14).

$$SSIM = \frac{\left(2\mu_x\mu_y + C_1\right)\left(2\sigma_{xy} + C_2\right)}{\left(\mu_x^2 + \mu_y^2 + C_1\right)\left(\mu_x^2 + \mu_y^2 + C_2\right)}$$
(14)

it has been observed that the SSIM values are nearest to 1, which shows that the cover and the stego both are prone to parallel and our human visual system can't recognize the changes occurred in the images.

#### F. K L Divergence (KLDIVG):

With the help of probability density function (PDF) for each Image (cover and stego) we estimate the Kullback-Leibler Divergence [48]. KL divergence shows in (15):

$$D(p \parallel q) = \sum_{x} p(x) \log \frac{p(x)}{q(x)}$$
(15)

#### G.Entropy:

Entropy is a measure of the uncertainty associated with a random variable [49]. Here, a 'message' means a specific

realization of the random variable. Equation (16) shows it.

$$\Delta S = \int \frac{dQ_{rev}}{T} \tag{16}$$

where, S is the entropy; T is the uniform thermodynamic temperature of a closed system divided into an incremental reversible transfer of heat into that system (dQ).

Here we have tested through some steganalysis technique because to access the security of the Steganography algorithm the attack is necessary. First exact detector of LSB replacement was the heuristic RS analysis [50. Then Sample Pairs (SP) analysis was analyzed and reformulated by

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Dumitrescu et al. [51] in 2002. In this work all the stego image is generated by the help of our algorithm and tested through steganalysis attack algorithm i.e. RS analysis. Fig. 15 shows the Analysis of attack of an RGB image (anu.jpg is used here) as cover and stego image. With the help of RS Analysis, we observe that, a typical images  $R_{COVER} \approx R_{STEGO}$  and  $S_{COVER} \approx S_{STEGO}$  and so no changes found in R and S value for embedding characters of different sizes.

#### VI. COMPARISON

The comparison with other methods belongs to special as well as frequency domains are furnished below.

TABLE I
MPARISON WITH OTHER SPATIAL DOMAIN STEGANOGRAPHIC METHOD

<b>Other Methods</b> [53], [54])	This Method
There is no embedding space determining concept per pixel.	Embedding space is determined per pixel by using a series of squared integers. ( $a_{ij}$ and $\beta_{ij}$ )
Message image is embedded directly.	Message image is not embedded directly but a polynomial $\sum^{n}$ is used which divides different length bit streams into different classes depending upon the value of k.
Embedding space does not vary from pixel to pixel.	Embedding space varies from pixel to pixel so that it may happen that no embedding is done for a pixel which ensures its security.
Stop bit is needed to denote the end of embedding.	Stop bit concept is not introduced here so that there are no such pixels which have different value form the other pixels which can be recognized easily.
For most of the methods one bit binary data is embedded.	0 or 1 or 2 or 3 or 4 bits of the message bit stream is embedded per pixel and if there is no sufficient embedding space for a plane then embedding is perform for the next plane.

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۱D		

TABLE II			
COMPARISON WITH OTHER FREQUENCY DOMAIN BIOMETRIC STEGANOGRAPHIC METHOD			
Others Methods [52]	This Method		
Frequency domain has used.	Spatial domain is using, but it can work on frequency domain also.		
Direct message embedding has been used.	Direct message is not embedding here.		
Variable length cannot be supported by this method.	Variable length has been supported by this method.		

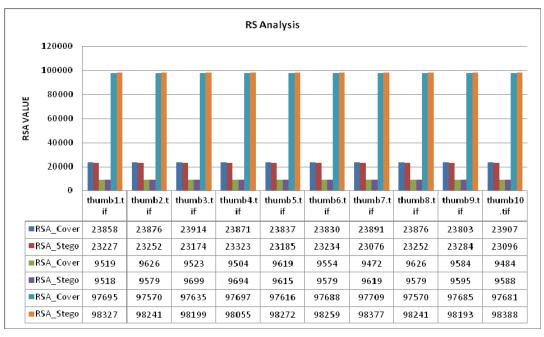


Fig. 15 RS Analysis for various Secret Images

#### VII. CONCLUSIONS

In this technique an image steganography process has been occurs by using a series for embedding space selection and a polynomial has been used for embedding the secret message, so that secret message bit is not embedded directly and makes difficult for steganalysis. Also for pixel selection mechanism, the biometric features has been used which comes from both the cover and secret embedding information. From the security aspects the attack technique is very low between the cover image and stego image which have already surrender a very high security value of the hidden data. The hidden message also keeps on undetected after appliance of some renowned steganalysis method on it. In future we have planned to apply this technique in frequency domain for better security and furthermore outspread the practice in video domain.

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