Numerical Study on the Flow around a Steadily Rotating Spring: Understanding the Propulsion of a Bacterial Flagellum

Won Yeol Choi, Sangmo Kang

Abstract—The propulsion of a bacterial flagellum in a viscous fluid has attracted many interests in the field of biological hydrodynamics, but remains yet fully understood and thus still a challenging problem. In this study, therefore, we have numerically investigated the flow around a steadily rotating micro-sized spring to further understand such bacterial flagellum propulsion. Note that a bacterium gains thrust (propulsive force) by rotating the flagellum connected to the body through a bio motor to move forward. For the investigation, we convert the spring model from the micro scale to the macro scale using a similitude law (scale law) and perform simulations on the converted macro-scale model using a commercial software package, CFX v13 (ANSYS).

In this study, it is helpful for us to understand thrust or propulsive force of bacteria having flagellar and the study help us to gain knowledge on hydrodynamic phenomena of swimming motion in the laminar region as well.

II. MATHEMATICAL MODELING

A. Numerical Analysis Model and Method

Fig. 1 Numerical model

In this study, performed analysis model such as a spring-like shape (Fig. 1) was used and similitude is applied for better visualization of flows. The spring that \( L = 200 \text{mm} \), \( \lambda = 66 \text{mm} \), \( R = 12.7 \text{mm} \), \( r = 1 \text{mm} \) is analyzed [3].

First, velocity field and pressure field are observed using the spring with \( L = 200 \text{mm} \), \( \lambda = 66 \text{mm} \), \( R = 12.7 \text{mm} \), \( r = 1 \text{mm} \). The propulsive force is calculated by changing each helical radius (\( R \)) and pitch (\( \lambda \)) to find out the correlation between geometric variation and the force, and similarly, the same model is also calculated with changing viscosity of fluid and rotational speed.

The Reynold’s number is given by [4]

\[
R_e = \frac{\omega \lambda^2 \rho}{\mu}
\]  

where \( \omega \) is rotational speed, \( \lambda \) is pitch, \( \rho \) is density and \( \mu \) is viscosity.

The Reynold’s number is kept between \( 10^{-3} \) and \( 10^{-5} \). And the governing equation is below [5]

\[
\nabla \cdot \mathbf{U} = 0
\]  

Keywords—Fluid viscosity, hydrodynamics, similitude, propulsive force.

I. INTRODUCTION

The propulsion of a bacterial flagellum in a viscous fluid has attracted many interests in the field of biological hydrodynamics, but remains yet fully understood and thus still a challenging problem. In this study, therefore, we have numerically investigated the flow around a steadily rotating micro-sized spring to further understand such bacterial flagellum propulsion. Note that a bacterium gains thrust (propulsive force) by rotating the flagellum connected to the body through a bio motor to move forward. Many prokaryotic bacteria like *Escherichia coli* during chemotaxis, swim towards or away from certain chemicals using their flagella [1]. It has been proved experimentally that it is flagellar rotation that causes swimming motion [2]. For the investigation, we convert the spring model from the micro scale to the macro scale using a similitude law (scale law) and perform simulations on the converted macro-scale model using a commercial software package, CFX v13 (ANSYS).

Won Yeol Choi is a Master of Engineering student with the School of Mechanical Engineering, University of Donga, Busan, Korea (e-mail: euvio@naver.com).

Sangmo Kang is the Faculty of Engineering with the School of Mechanical Engineering, University of Donga, Busan, Korea (e-mail: kangsm@dau.ac.kr).
\[ \rho \frac{d\mathbf{u}}{dt} + \rho (\mathbf{u} \cdot \nabla)\mathbf{u} = -\nabla p + \mu \nabla^2 \mathbf{u} \]  

(3)

There are two methods. One is inner cylinder rotation that means the inner cylinder-shaped domain is rotated and outer cylinder-shaped domain is stationary and then solution is calculated in terms of absolute coordinate system (Fig. 2). The other is outer cylinder rotation that the inner cylinder-shaped is not present and only one cylinder-shaped domain is rotated, and then solution is calculated in terms of relative coordinate system (Fig. 3).

B. Analysis Grid and Condition

In this study, owing to the curvature of the spring, tetrahedral grid was used. Inlet and outlet were applied with both opening condition and pressure condition, and the outer cylinder and inner cylinder were given a no-slip condition, additionally the inner cylinder was given rotating speed. Steady-state analysis of laminar model was performed for numerical convergence and improved accuracy.

III. RESULT

A. Validation

Similar results were obtained in the velocity field and the pressure field around the spring between rotation of the inner cylinder and the outer cylinder. Thus, rotation of the inner cylinder is used in this paper.

Fig. 2 First method (inner cylinder rotation)

Fig. 3 Second method (outer cylinder rotation)

Fig. 4 Comparison between rotation of the inner cylinder (a) and rotation of the outer cylinder (b) in velocity field

Fig. 5 Comparison between rotation of the inner cylinder (a) and rotation of the outer cylinder (b) in pressure field

B. Analysis Result

Fig. 6 Effect of the square of the radius on thrust force (propulsive force)
Finally, the force linearly increases with increasing viscosity of fluid (Fig. 9).

IV. CONCLUSION

The study for parameters was conducted by numerical analysis on fluid flow around spring in laminar flow. The propulsion characteristics depend strongly on the parameters mentioned above. It is observed that the forward thrust increases in a linear fashion with either of the rotational speed or the fluid viscosity. In addition, the thrust is directly proportional to square of the helical radius but the thrust force is increased and then decreased based on the peak value to the pitch, and maximum value of force is found.

Finally, we also present the appropriate flow and pressure fields visualized to support the observations.

ACKNOWLEDGMENT

This work was supported by the BK21 plus Project and by the Human Resources Development of the Korea Institute of Energy Technology Evaluation and Planning (KETEP) grant funded by the Korea government Ministry of Knowledge Economy (No. 20114030200030).

REFERENCES


Won Yeol, Choi was born in Busan, Korea in 1987. He received the B. S. degree in Mechanical Engineering, Dong-A university, Busan, Korea in 2103. He is working toward to M.S. degree in the Department of Mechanical Engineering, Dong-A university, Busan, Korea. His research interests are in Computational Fluid Dynamics.